(servo motor)

include <Servo.h>

Servo servo\_11;

Servo servo\_10;

int i;

void setup() {

servo\_11.attach(11);

servo\_10.attach(10);

}

void loop() {

for (i = 0; i <= 180; i++) {

servo\_11.write(i);

servo\_10.write(i);

delay(500);

for (i = 180; i >= 0; i--) {

servo\_11.write(i);

servo\_10.write(i);

delay(500);

}

}

}

التطبيق

<https://www.tinkercad.com/things/aor209QmdoM-start-simulating/editel?lessonid=EHD2303J3YPUS5Z&projectid=OIYJ88OJ3OPN3EA&collectionid=OIYJ88OJ3OPN3EA&tenant=circuits#/lesson-viewer?sharecode=IxD06stAbfT1lItfi4oZE3OT_O-mBjK4CQPu6cZnUpo>